

Gaussian random projections for Euclidean membership problems

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Abstract

We discuss the application of random projections to the fundamental problem of deciding whether a given point in a Euclidean space belongs to a given set. We show that, under a number of different assumptions, the feasibility and infeasibility of this problem are preserved with high probability when the problem data is projected to a lower dimensional space. Our results are applicable to any algorithmic setting which needs to solve Euclidean membership problems in a high-dimensional space.

1 Introduction

Random projections are very useful dimension reduction techniques which are widely used in computer science [7, 13]. We assume we have an algorithm \mathcal{A} acting on a data set X consisting of n vectors in \mathbb{R}^m , where m is large, and assume that the complexity of \mathcal{A} depends on m and n in a way that makes it impossible to run \mathcal{A} sufficiently fast. A random projection exploits the statistical properties of some random distribution to construct a mapping which embeds X into a lower dimensional space \mathbb{R}^k (for some appropriately chosen k) while preserving distances, angles, or other quantities used by \mathcal{A} .

One striking example of random projections is the famous Johnson-Lindenstrauss lemma [9]:

1.1 Theorem (Johnson-Lindenstrauss Lemma)

Let X be a set of m points in \mathbb{R}^m and $\varepsilon > 0$. Then there is a map $F : \mathbb{R}^m \rightarrow \mathbb{R}^k$ where k is $O(\frac{\log m}{\varepsilon^2})$, such that for any $x, y \in X$, we have

$$(1 - \varepsilon)\|x - y\|_2^2 \leq \|F(x) - F(y)\|_2^2 \leq (1 + \varepsilon)\|x - y\|_2^2. \quad (1)$$

Intuitively, this lemma claims that X can be projected in a much lower dimensional space whilst keeping Euclidean distances approximately the same. The main idea to prove Thm. 1.1 is to construct a random linear mapping T (called *JL random mapping* onwards), sampled from certain distribution families, so that for each $x \in \mathbb{R}^m$, the event that

$$(1 - \varepsilon)\|x\|_2^2 \leq \|T(x)\|_2^2 \leq (1 + \varepsilon)\|x\|_2^2 \quad (2)$$

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occurs with high probability. By Eq. (2) and the union bound, it is possible to show the existence of a map F with the stated properties (see [2, 4]).

In this paper we employ random projections to study the following general problem:

EUCLIDEAN SET MEMBERSHIP PROBLEM (ESMP). Given $p \in \mathbb{R}^m$ and $X \subseteq \mathbb{R}^m$, decide whether $p \in X$.

This is a fundamental class consisting of many problems, both in **P** (e.g. the **LINEAR FEASIBILITY PROBLEM (LFP)**) and **NP**-hard (e.g. the **INTEGER FEASIBILITY PROBLEM (IFP)**), which can naturally model SAT, and also see [15]).

In this paper, we use a random linear projection operator T to embed both p and X to a lower dimensional space, and study the relationship between the original membership problem and its projected version:

PROJECTED ESMP (PESMP). Given p, X, T as above, decide whether $T(p) \in T(X)$.

Note that, when $p \in X$, the fact that $T(p) \in T(X)$ follows by linearity of T . We are therefore only interested in the case when $p \notin X$, i.e. we want to estimate $\text{Prob}(T(p) \notin T(X))$, given that $p \notin X$.

1.1 Previous results

Random projections applying to some special cases of membership problems have been studied in [11], where we exploited some polyhedral structures of the problem to derive several results for polytopes and polyhedral cones. In the case X is a polytope, we obtained the following result.

1.2 Proposition ([11])

Given $a_1, \dots, a_n \in \mathbb{R}^m$, let $C = \text{conv}\{a_1, \dots, a_n\}$, $b \in \mathbb{R}^m$ such that $b \notin C$, $d = \min_{x \in C} \|b - x\|$ and $D = \max_{1 \leq i \leq n} \|b - a_i\|$. Let $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a JL random mapping. Then

$$\text{Prob}(T(b) \notin T(C)) \geq 1 - 2n^2 e^{-C(\varepsilon^2 - \varepsilon^3)k}$$

for some constant C (independent of m, n, k, d, D) and $\varepsilon < \frac{d^2}{D^2}$.

If X is a polyhedral cone, we obtained the following result.

1.3 Proposition ([11])

Given $b, a_1, \dots, a_n \in \mathbb{R}^m$ of norms 1 such that $b \notin C = \text{cone}\{a_1, \dots, a_n\}$, let $d = \min_{x \in C} \|b - x\|$ and $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a JL random mapping. Then:

$$\text{Prob}(T(b) \notin T(C)) \geq 1 - 2n(n+1)e^{-C(\varepsilon^2 - \varepsilon^3)k}$$

for some constant C (independent of m, n, k, d), where $\varepsilon = \frac{d^2}{\mu_A^2 + 2\sqrt{1-d^2}\mu_A + 1}$,

$$\mu_A = \max\{\|x\|_A \mid x \in \text{cone}(a_1, \dots, a_n) \wedge \|x\| \leq 1\},$$

and $\|x\|_A = \min\{\sum_i \theta_i \mid \theta \geq 0 \wedge x = \sum_i \theta_i a_i\}$ is the norm induced by $A = (a_1, \dots, a_n)$.

We also recall the following Lemma, useful for the integer case.

1.4 Lemma ([11])

Let $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a JL random mapping, let $b, a_1, \dots, a_n \in \mathbb{R}^m$ and let $X \subseteq \mathbb{R}^m$ be a finite set. Then if $b \neq \sum_{i=1}^m y_i a_i$ for all $y \in X$, we have

$$\text{Prob} \left(\forall y \in X \mid T(b) \neq \sum_{i=1}^m y_i T(a_i) \right) \geq 1 - 2|X|e^{-Ck};$$

for some constant $C > 0$ (independent of m, k).

1.2 New results

In this paper, we consider the general case where the data set X has no specific structure, and use Gaussian random projections in our arguments to obtain some results about the relationship between ESMP and PESMP.

In the case when X is at most countable (i.e. finite or countable), using a straightforward argument, we prove that these two problems are equivalent almost surely. However, this result is only of theoretical interest due to round-off errors in floating point operations, which make its practical application difficult. We address this issue by introducing a threshold $\delta > 0$ with a corresponding THRESHOLD ESMP (TESMP): if Δ is the distance between $T(p)$ and the closest point of $T(X)$, decide whether $\Delta \geq \delta$.

In the case when X may also be uncountable, we employ the *doubling constant* of X , i.e. the smallest number λ_X such that any closed ball in X can be covered by at most λ_X closed balls of half the radius. Its logarithm $\log_2 \lambda_X$ is called *doubling dimension* of X . Recently, the doubling dimension has become a powerful tool for several classes of problems such as nearest neighbor [10, 8], low-distortion embeddings [3], clustering [12].

We show that we can project X into \mathbb{R}^k , where $k = O(\log_2 \lambda_X)$, whilst still ensure the equivalence between ESMP and PESMP with high probability. We also extend this result to the threshold case, and obtain a more useful bound for k .

2 Finite and countable sets

In this section, we assume that X is either finite or countable. Let T be a JL random mapping from a Gaussian distribution, i.e. each entry of T is independently sampled from $\mathcal{N}(0, 1)$. It is well known that, for an arbitrary unit vector $a \in \mathbb{S}^{m-1}$, the random variable $\|Ta\|^2$ has a Chi-squared distribution χ_k^2 with k degrees of freedom ([14]). Its corresponding density function is $\frac{2^{-k/2}}{\Gamma(k/2)} x^{k/2-1} e^{-x/2}$, where $\Gamma(\cdot)$ is the gamma function. By [4], for any $0 < \delta < 1$, taking $z = \frac{\delta}{k}$ yields a cumulative distribution function

$$F_{\chi_k^2}(\delta) \leq (ze^{1-z})^{k/2} < (ze)^{k/2} = \left(\frac{e\delta}{k} \right)^{k/2}. \quad (3)$$

Thus, we have

$$\text{Prob}(\|Ta\| \leq \delta) = F_{\chi_k^2}(\delta^2) < (3\delta^2)^{k/2} \quad (4)$$

or, more simply, $\text{Prob}(\|Ta\| \leq \delta) < \delta^k$ when $k \geq 3$.

Using this estimation, we immediately obtain the following result.

2.1 Proposition

Given $p \in \mathbb{R}^m$ and $X \subseteq \mathbb{R}^m$, at most countable, such that $p \notin X$. Then, for a Gaussian random projection $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ with any $k \geq 1$, we have $T(p) \notin T(X)$ almost surely, i.e. $\text{Prob}(T(p) \notin T(X)) = 1$.

Proof. First, note that for any $u \neq 0$, $Tu \neq 0$ holds almost certainly. Indeed, without loss of generality we can assume that $\|u\| = 1$. Then for any $0 < \delta < 1$:

$$\text{Prob}(T(z) = 0) \leq \text{Prob}(\|Tz\| \leq \delta) = (3\delta^2)^{k/2} \rightarrow 0 \text{ as } \delta \rightarrow 0.$$

Since the event $T(p) \notin T(X)$ can be written as the intersection of at most countably many almost sure events $T(p) \neq T(x)$ (for $x \in X$), it follows that $\text{Prob}(T(p) \notin T(X)) = 1$, as claimed. \square

Proposition 2.1 is simple, but it looks interesting because it suggests that we only need to project the data points to a line (i.e. $k = 1$) and study an equivalent membership problem on a line. Furthermore, it turns out that this result remains true for a large class of random projections.

2.2 Proposition

Let ν be a probability distribution on \mathbb{R}^m with bounded Lebesgue density f . Let $Y \subseteq \mathbb{R}^m$ be an at most countable set such that $0 \notin Y$. Then, for a random projection $T : \mathbb{R}^m \rightarrow \mathbb{R}^1$ sampled from ν , we have $0 \notin T(Y)$ almost surely, i.e. $\text{Prob}(0 \notin T(Y)) = 1$.

Proof. For any $0 \neq y \in Y$, consider the set $\mathcal{E}_y = \{T : \mathbb{R}^m \rightarrow \mathbb{R}^1 \mid T(y) = 0\}$. If we regard each $T : \mathbb{R}^m \rightarrow \mathbb{R}^1$ as a vector $t \in \mathbb{R}^m$, then \mathcal{E}_y is a hyperplane $\{t \in \mathbb{R}^m \mid y \cdot t = 0\}$ and we have

$$\text{Prob}(T(y) = 0) = \nu(\mathcal{E}_y) = \int_{\mathcal{E}_y} f d\mu \leq \|f\|_\infty \int_{\mathcal{E}_y} d\mu = 0$$

where μ denotes the Lebesgue measure on \mathbb{R}^m . The proof then follows by the countability of Y , similarly to Proposition 2.1. \square

Proposition 2.2 is based on the observation that the degree $[\mathbb{R} : \mathbb{Q}]$ of the field extension \mathbb{R}/\mathbb{Q} is 2^{\aleph_0} , whereas Y is countable; so the probability that any row vector T_i of the random projection matrix T will yield a linear dependence relation $\sum_{j \leq m} T_{ij} y_j = 0$ for some $0 \neq y \in Y$ is zero. In practice, however, Y is part of the rational input of a decision problem, and the components of T are rational: hence any subsequence of them is trivially linearly dependent over \mathbb{Q} . Moreover, floating point numbers have a bounded binary representation: hence, even if Y is finite, there is a nonzero probability that any subsequence of components of T will be linearly dependent by means of a nonzero multiplier vector in Y .

This idea, however, does not work in practice: we tested it by considering the ESMP given by the IPF defined on the set $\{x \in \mathbb{Z}_+^n \cap [L, U] \mid Ax = b\}$. Numerical experiments indicate that the corresponding PESMP $\{x \in \mathbb{Z}_+^n \cap [L, U] \mid T(A)x = T(b)\}$, with T consisting of a one-row Gaussian projection matrix, is always feasible despite the infeasibility of the original IPF. Since Prop. 2.1

assumes that the components of T are real numbers, we think that the reason behind this failure is the round-off error associated to the floating point representation used in computers. Specifically, when $T(A)x$ is too close to $T(b)$, floating point operations will consider them as a single point. In order to address this issue, we force the projected problems to obey stricter requirements. In particular, instead of only requiring that $T(p) \notin T(X)$, we ensure that

$$\text{dist}(T(p), T(X)) = \min_{x \in X} \|T(p) - T(x)\| > \tau,$$

where dist denotes the Euclidean distance, and $\tau > 0$ is a (small) given constant. With this restriction, we obtain the following result.

2.3 Proposition

Given $\tau, \delta > 0$ and $p \notin X \subseteq \mathbb{R}^m$, where X is a finite set, let

$$d = \min_{x \in X} \|p - x\| > 0.$$

Let $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a Gaussian random projection with $k \geq \frac{\log(\frac{|X|}{\delta})}{\log(\frac{d}{\tau})}$. Then:

$$\text{Prob}\left(\min_{x \in X} \|T(p) - T(x)\| > \tau\right) > 1 - \delta.$$

Proof. We assume that $k \geq 3$. For any $x \in X$ we have:

$$\begin{aligned} \text{Prob}(\|T(p - x)\| \leq \tau) &= \text{Prob}\left(\left\|T\left(\frac{p - x}{\|p - x\|}\right)\right\| \leq \frac{\tau}{\|p - x\|}\right) \\ &\leq \text{Prob}\left(\left\|T\left(\frac{p - x}{\|p - x\|}\right)\right\| \leq \frac{\tau}{d}\right) < \frac{\tau^k}{d^k}, \end{aligned}$$

due to (3). Therefore, by the union bound,

$$\begin{aligned} \text{Prob}\left(\min_{x \in X} \|T(p) - T(x)\| > \tau\right) &= 1 - \text{Prob}\left(\min_{x \in X} \|T(p) - T(x)\| \leq \tau\right) \\ &\geq 1 - \sum_{x \in X} \text{Prob}(\|T(p) - T(x)\| \leq \tau) > 1 - |X| \left(\frac{\tau}{d}\right)^k. \end{aligned}$$

The RHS is greater than or equal to $1 - \delta$ if and only if $\left(\frac{d}{\tau}\right)^k \geq \frac{|X|}{\delta}$, which is equivalent to $k \geq \frac{\log(\frac{|X|}{\delta})}{\log(\frac{d}{\tau})}$, as claimed. \square

Note that d is often unknown and can be arbitrarily small. However, if both p, X are integral, then $d \geq 1$ and we can select $k > \frac{\log \frac{|X|}{\delta}}{\log \frac{1}{\tau}}$ in the above proposition.

In many cases, the set X is infinite. We show that when this is the case, we can still overcome this difficulty under some assumptions. In particular, we prove that if $X = \{Ax \mid x \in \mathbb{Z}_+^n\}$ where A is an $m \times n$ matrix with integer coefficients which are all positive in at least one row, then for any bounded vector $b \in \mathbb{Z}^m$ the problem $b \in X$ is equivalent, with high probability, to its projection to a $O(\log n)$ -dimensional space. The idea is to separate one positive row and apply random projection to the others.

Formally, let us denote by a^i the i -th row and by a_j the j -th column of A . Assume that all entries in the row a^i is positive and all entries of b are bounded by a constant $B > 0$. Remove the row i from A and b to obtain $\tilde{A} = (a'_1, \dots, a'_n) \in \mathbb{Z}^{(m-1) \times n}$ and $\tilde{b} \in \mathbb{Z}^{m-1}$. Let $T : \mathbb{R}^{m-1} \rightarrow \mathbb{R}^k$ be a JL random mapping and denote by $Z = \{x \in \mathbb{Z}_+^n \mid a^i \cdot x = b_i\}$. Then we have:

2.4 Proposition

Assume that $b \notin X$, and let $0 < \delta < 1$. Using the terminology and given the assumptions above, if $k \geq \frac{1}{C} \ln(\frac{2}{\delta}) + \frac{B}{C} \log(n + B - 1)$ we have

$$\text{Prob}\left(T(b) \neq \sum_{j=1}^n x_j T(a'_j) \text{ for all } x \in Z\right) \geq 1 - \delta$$

for some constant $C > 0$.

Proof. We first show that $|Z| \leq (n + B - 1)^B$. Since all the entries of A are positive integers, we have

$$|Z| \leq |\{x \in \mathbb{Z}_+^n \mid \sum_{j=1}^n x_j = b_i\}| \leq |\{x \in \mathbb{Z}_+^n \mid \sum_{j=1}^n x_j = B\}|.$$

The number of elements in the RHS corresponds to the number of combinations with repetitions of B items sampled from n , which is equal to $\binom{n+B-1}{n-1} = \binom{n+B-1}{B} \leq (n + B - 1)^B$.

Next, by Lemma 1.4, we have:

$$\text{Prob}\left(T(b) \neq \sum_{j=1}^n x_j T(a'_j) \text{ for all } x \in Z\right) \geq 1 - 2(n + B - 1)^B e^{-Ck}, \quad (5)$$

which is greater than $1 - \delta$ when taking any k such that $k \geq \frac{1}{C} \ln(\frac{2}{\delta}) + \frac{B}{C} \log(n + B - 1)$. The proposition is proved. \square

Note that in Prop. 2.4 we can choose the JL random mapping T as a matrix with $\{-1, +1\}$ entries (Rademacher variables). In this case, there is no need to worry about floating point errors.

3 Sets with low doubling dimension

In this section, we denote by $B(x, r)$ the closed ball centered at x with radius $r > 0$, and $B_X(x, r) = B(x, r) \cap X$. We will also assume that X is a doubling space, i.e. a set with bounded doubling dimension. One example of doubling spaces is a Euclidean space. \mathbb{R}^m , we can show that the doubling dimension $\log_2(\lambda_X)$ of X can be shown to be a constant factor of m ([16, 6]). However, many sets of low doubling dimensions are contained in high dimensional spaces ([1]). Note that computing the doubling dimension of a metric space is generally **NP**-hard ([5]). We shall make use of the following simple lemma.

3.1 Lemma

For any $p \in X$ and $\varepsilon, r > 0$, there is a set $S \subseteq X$ of size at most $\lambda_X^{\lceil \log_2(\frac{r}{\varepsilon}) \rceil}$ such that

$$B_X(p, r) \subseteq \bigcup_{s \in S} B(s, \varepsilon).$$

Proof. By definition of the doubling dimension, $B_X(p, r)$ is covered by at most λ_X closed balls of radius $\frac{r}{2}$. Each of these balls in turn is covered by λ_X balls of radius $\frac{r}{4}$, and so on: iteratively, for each $k \geq 1$, $B_X(p, r)$ is covered by λ_X^k balls of radius $\frac{r}{2^k}$. If we select $k = \lceil \log_2(\frac{r}{\varepsilon}) \rceil$ then $k \geq \log_2(\frac{r}{\varepsilon})$, i.e. $\frac{r}{2^k} \leq \varepsilon$. This means $B_X(p, r)$ is covered by $\lambda_X^{\lceil \log_2(\frac{r}{\varepsilon}) \rceil}$ balls of radius ε . \square

We will also use the following lemma, which is proved in [8] using a concentration estimation for sum of squared gaussian variables (Chi-squared distribution).

3.2 Lemma

Let $X \subseteq B(0, 1)$ be a subset of the m -dimensional Euclidean unit ball. Then there exist universal constants $c, C > 0$ such that for $k \geq C \log \lambda_X + 1$ and $\delta > 1$, the following holds:

$$\text{Prob}(\exists x \in X \text{ s.t. } \|Tx\| > \delta) < e^{-c\delta^2}.$$

In the proof of the next result (one of the main results in this section), we use the same idea as that in [8] for the nearest neighbor problem.

3.3 Theorem

Given $0 < \delta < 1$ and $p \notin X \subseteq \mathbb{R}^m$. Let $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a Gaussian random projection. Then

$$\text{Prob}(T(p) \notin T(X)) = 1$$

if $k \geq C \log_2(\lambda_X)$, for some universal constant C .

Proof. Let $\varepsilon > 0$ and $0 = r_0 < r_1 < r_2 < \dots$ be positive scalars (their values will be defined later). For each $j = 1, 2, 3, \dots$ we define a set

$$X_j = X \cap B(p, r_j) \setminus B(p, r_{j-1}).$$

Since $X_j \subseteq B_X(p, r_j)$, by Lemma 3.1 we can find a point set $S_j \subseteq X$ of size $|S_j| \leq \lambda_X^{\lceil \log_2(\frac{r_j}{\varepsilon}) \rceil}$ such that

$$X_j \subseteq \bigcup_{s \in S_j} B(s, \varepsilon).$$

Hence, for any $x \in X_j$, there is $s \in S_j$ such that $\|x - s\| < \varepsilon$. Moreover, by the triangle inequality, any such s satisfies $r_{j-1} - \varepsilon < \|s - p\| < r_j + \varepsilon$, so without loss of generality we can assume that

$$S_j \subseteq B(p, r_j + \varepsilon) \setminus B(p, r_{j-1} - \varepsilon).$$

We denote by \mathcal{E}_j the event that:

$$\exists s \in S_j, \exists x \in X_j \cap B(s, \varepsilon) \text{ s.t. } \|Ts - Tx\| > \varepsilon \sqrt{j}.$$

By the union bound, we have

$$\begin{aligned} \text{Prob}(\mathcal{E}_j) &\leq \sum_{s \in S_j} \text{Prob}(\exists x \in X_j \cap B(s, \varepsilon) \text{ s.t. } \|Ts - Tx\| > \varepsilon \sqrt{j}) \\ &\leq \sum_{s \in S_j} e^{-c_1 k j} \quad (\text{for some universal constant } c_1 \text{ by Lemma 3.2}) \\ &\leq \lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} e^{-c_1 k j}. \end{aligned}$$

Again by the union bound, we have:

$$\begin{aligned} \text{Prob}(\exists x \in X \text{ s.t. } T(x) = T(p)) &= \text{Prob}(\exists x \in \bigcup_{j=1}^{\infty} X_j \text{ s.t. } T(x) = T(p)) \\ &\leq \sum_{j=1}^{\infty} \text{Prob}(\exists x \in X_j \text{ s.t. } T(x) = T(p)). \end{aligned}$$

Now we will estimate the individual probabilities:

$$\begin{aligned} &\text{Prob}(\exists x \in X_j \text{ s.t. } T(x) = T(p)) \\ &\leq \text{Prob}((\exists x \in X_j \text{ s.t. } T(x) = T(p)) \wedge \mathcal{E}_j^c) + \text{Prob}(\mathcal{E}_j) \\ &\leq \text{Prob}(\exists x \in X_j, s \in S_j \cap B(x, \varepsilon) \text{ s.t. } T(x) = T(p) \wedge \|T(s) - T(x)\| \leq \varepsilon\sqrt{j}) + \text{Prob}(\mathcal{E}_j) \\ &\leq \text{Prob}(\exists s \in S_j \text{ s.t. } \|T(s) - T(p)\| < \varepsilon\sqrt{j}) + \lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} e^{-c_1 k j}. \end{aligned}$$

Next, we choose $\varepsilon = \frac{d}{N}$ for some large N ; and for each $j \geq 1$, we choose $r_j = (2+j)\varepsilon$. For $j < N-2$, by definition it follows that $X_j = \emptyset$. Therefore

$$\text{Prob}(\exists x \in X_j \text{ s.t. } T(s) = T(p)) = 0.$$

On the other hand, for $j \geq N-2$,

$$\begin{aligned} &\text{Prob}(\exists s \in S_j \text{ s.t. } \|T(s) - T(p)\| \leq \varepsilon\sqrt{j}) \\ &\leq \lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} \text{Prob}(\|T(z)\| \leq \frac{\varepsilon\sqrt{j}}{r_{j-1} - \varepsilon}) \quad \text{for an arbitrary } z \in \mathbb{S}^{n-1} \\ &= \lambda_X^{\lceil \log_2(3+j) \rceil} \text{Prob}(\|T(z)\| \leq \frac{1}{\sqrt{j}}) \quad \text{for an arbitrary } z \in \mathbb{S}^{n-1} \\ &< \lambda_X^{\lceil \log_2(3+j) \rceil} j^{-k/2} \quad \text{by the estimation (4)}. \end{aligned}$$

Note that $\lambda_X^{\lceil \log_2(3+j) \rceil} \leq \lambda_X^{\log_2(6+2j)} = (6+2j)^{\log_2 \lambda_X} < j^{(2 \log_2 \lambda_X)}$ for large enough N . Therefore, we have

$$\begin{aligned} \text{Prob}(\exists x \in X_j \text{ s.t. } T(x) = T(p)) &\leq \lambda_X^{\lceil \log_2(3+j) \rceil} (j^{-k/2} + e^{-c_1 k j}) \\ &\leq j^{-c_2 k} + e^{-c_3 k j} \end{aligned}$$

for some universal constants c_2, c_3 , provided that $k \geq \mathcal{C}_1 \log \lambda_X$ for some large enough constant \mathcal{C}_1 . Finally, by the union bound,

$$\begin{aligned} \text{Prob}(T(p) \notin T(X)) &= 1 - \text{Prob}(T(p) \in T(X)) \\ &\geq 1 - \sum_{i=N-2}^{\infty} (i^{-c_2 k} + e^{-c_3 k i}) \end{aligned}$$

which tends to 1 when N tends to infinity. □

Our final result in the section is an extension of Thm. 3.3 to the threshold case.

3.4 Theorem

Let $p \notin X \subseteq \mathbb{R}^m$, $T : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be a Gaussian random projection, and $d = \min_{x \in X} \|p - x\|$. Then for all $0 < \delta < 1$ and all $0 < \tau < \kappa d$ for some constant $\kappa < 1$, we have

$$\text{Prob}(\text{dist}(T(p), T(X)) > \tau) > 1 - \delta$$

if k is $O(\frac{\log(\frac{\lambda_X}{\delta})}{\log(\frac{d}{\tau})})$.

Proof. For $j = 1, 2, \dots$ we construct the sets X_j, S_j similarly as those in the proof of Thm. 3.3 (where the values of r_j and ε will be defined later). Then we have

$$\begin{aligned} \text{Prob}(\exists x \in X \text{ s.t. } \|T(x) - T(p)\| < \tau) &= \text{Prob}(\exists x \in \bigcup_{j=1}^{\infty} X_j \text{ s.t. } \|T(x) - T(p)\| < \tau) \\ &\leq \sum_{j=1}^{\infty} \text{Prob}(\exists x \in X_j \text{ s.t. } \|T(x) - T(p)\| < \tau). \end{aligned}$$

For all $j \geq 1$, we have

$$\begin{aligned} &\text{Prob}(\exists x \in X_j \text{ s.t. } \|T(x) - T(p)\| < \tau) \\ &\leq \text{Prob}((\exists x \in X_j \text{ s.t. } \|T(x) - T(p)\| < \tau) \wedge \mathcal{E}_j^c) + \text{Prob}(\mathcal{E}_j) \\ &\leq \text{Prob}(\exists x \in X_j, s \in S_j \cap B(x, \varepsilon) \text{ s.t. } \|T(x) - T(p)\| < \tau \wedge \|T(s) - T(x)\| \leq \varepsilon \sqrt{j}) + \text{Prob}(\mathcal{E}_j) \\ &\leq \text{Prob}(\exists s \in S_j \text{ s.t. } \|T(s) - T(p)\| < \tau + \varepsilon \sqrt{j}) + \lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} e^{-c_1 k j}. \end{aligned}$$

Now we choose $\varepsilon = \frac{\tau}{N}$ for some $N > 0$ such that $1 + \frac{1}{N} < \frac{1}{\kappa}$ and for each $j \geq 1$, we choose $r_j = \tau \sqrt{j+1} + (2+j)\varepsilon$. For $j = 1$, by the union bound we have

$$\begin{aligned} &\text{Prob}(\exists s \in S_1 \text{ s.t. } \|T(s) - T(p)\| \leq \tau + \varepsilon \sqrt{1}) \\ &\leq \lambda_X^{\lceil \log_2(\frac{r_1 + \varepsilon}{\varepsilon}) \rceil} \text{Prob}(\|T(z)\| \leq \frac{\tau + \varepsilon}{d}) \quad \text{for an arbitrary } z \in \mathbb{S}^{m-1} \\ &= \lambda_X^{\lceil \log_2(4+N\sqrt{2}) \rceil} \text{Prob}\left(\|T(z)\| \leq (1 + \frac{1}{N})\frac{\tau}{d}\right) \quad \text{for an arbitrary } z \in \mathbb{S}^{m-1} \\ &< \lambda_X^{\lceil \log_2(4+N\sqrt{2}) \rceil} \left((1 + \frac{1}{N})\frac{\tau}{d}\right)^{k/2} \quad \text{by estimation (4)} \\ &< \left((1 + \frac{1}{N})\frac{\tau}{d}\right)^{c_2 k} \end{aligned} \tag{6}$$

for some universal constant $c_2 > 0$, as long as $k > \mathcal{C} \log(\lambda_X)$ for some \mathcal{C} large enough.

For $j \geq 2$, we have

$$\begin{aligned} &\text{Prob}(\exists s \in S_j \text{ s.t. } \|T(s) - T(p)\| \leq \tau + \varepsilon \sqrt{j}) \\ &\leq \lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} \text{Prob}(\|T(z)\| \leq \frac{\tau + \varepsilon \sqrt{j}}{r_{j-1} - \varepsilon}) \quad \text{for an arbitrary } z \in \mathbb{S}^{m-1} \\ &= \lambda_X^{\lceil \log_2(3+j+N\sqrt{j+1}) \rceil} \text{Prob}(\|T(z)\| \leq \frac{1}{\sqrt{j}}) \quad \text{for an arbitrary } z \in \mathbb{S}^{m-1} \\ &< \lambda_X^{\lceil \log_2(3+j+N\sqrt{j+1}) \rceil} j^{-k/2} \quad \text{by estimation (4)} \\ &< j^{-c_3 k} \end{aligned} \tag{7}$$

for some universal constant $c_3 > 0$, as long as $k > \mathcal{C} \log(\lambda_X)$ for some \mathcal{C} large enough.

Similarly, for all $1 \leq j$, we have

$$\lambda_X^{\lceil \log_2(\frac{r_j + \varepsilon}{\varepsilon}) \rceil} e^{-c_1 k j} \leq e^{-c_4 k j}, \quad (8)$$

for some universal constant $c_4 > 0$, as long as $k > \mathcal{C} \log(\lambda_X)$ for some \mathcal{C} large enough.

From estimations (6), (7), (8) and by the union bound we have:

$$\begin{aligned} \text{Prob}(\text{dist}(T(p), T(X)) \geq \tau) &\geq 1 - \sum_{j=1}^{\infty} \text{Prob}(\text{dist}(T(p), T(X_j)) < \tau) \\ &\geq 1 - \left(\left(1 + \frac{1}{N}\right) \frac{\tau}{d} \right)^{c_2 k} - \sum_{j=2}^{\infty} j^{-c_3 k} - \sum_{j=1}^{\infty} e^{-c_4 k j} \\ &\geq 1 - \delta \quad \text{for } k = O\left(\frac{\log(\frac{\lambda_X}{\delta})}{\log(\frac{d}{\tau})}\right) \text{ large enough.} \end{aligned}$$

□

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